· (cuyrounge multiplier (with multiple constroints)  

$$\begin{cases} SF = \lambda Sg & \longrightarrow \{SF = \lambda Sg, + \dots + \lambda sSg \} \\ g(c) = c & \{g^{(c)} = C_{i} \\ g^{(c)} = c & \{g^{(c)} = C_{i} \\ f^{(c)} = c & \{g^{(c)} = c \\ f^{(c)} = c & \{g^{(c)} = c \\ f^{(c)} = c$$

If this linear system not solvelle, 
$$y=y(x)$$
,  $z=20y$   
DNE.  
If it has a caliform (e.g.  $\begin{pmatrix} \partial F_{1} & \partial F_{1} \\ \partial \partial & \partial z \\ \partial F_{2} & \partial f_{2} \\ \partial F_{3} & \partial f_{3} \\ \partial F_{3} & \partial f_{2} \\ \partial F_{3} & \partial f_{3} \\ \partial F_{3} & \partial f_{2} \\ \partial F_{3} & \partial f_{3} \\ \partial F_{3} & \partial f_{2} \\ \partial F_{3} & \partial F_{3} \\ \partial F_{3} & \partial f_{2} \\ \partial F_{3} & \partial F_{3} \\ \partial$ 

Then (Jumplicit function theorem)  
Let 
$$\Sigma \in \mathbb{R}^{n+k}$$
 open  $f: \Sigma \to \mathbb{R}^{k}$  be  $C^{1}$   
Denote  $X = (x \cdots x_{n})$   $Y = (Y_{1} \cdots Y_{k})$   
 $f(x \cdot y) = \begin{pmatrix} f_{1}(x \cdot y) \\ \vdots \\ f_{n}(x \cdot y) \end{pmatrix}$ . Suppose  $(a,b) \in \Omega$   
 $\begin{pmatrix} a \in \mathbb{R}^{n} \\ b \in \mathbb{R}^{k} \end{pmatrix}$   
S.E.  $F(a,b) = C \in \mathbb{R}^{k}$  and the moderits  
 $\begin{bmatrix} \partial F_{n}(a,b) \\ \partial Y_{j} \end{bmatrix} = \begin{pmatrix} \partial f_{n}(a,b) \\ \vdots \\ \partial F_{n}(a,b) \\ \vdots \\ \partial F_{n}(a,b) \end{pmatrix} = \begin{pmatrix} \partial f_{n}(a,b) \\ \partial Y_{j}(a,b) \\ \partial Y_{j}(a,b) \\ \partial Y_{j}(a,b) \\ \partial Y_{j}(a,b) \end{pmatrix}$   
 $f(a,b) \cdots \\ f(a,b) \\ \partial Y_{k}(a,b) \\ \partial Y_{k}(a,b) \end{pmatrix}$   
 $f(a,b) \cdots \\ f(a,b) \\ f(a,b) \\ \partial Y_{k}(a,b) \\ (a,b) \\ f(a,b) \\ (a,b) \\$ 

 $\varphi = (\varphi, \cdots, \varphi_{k})$ By implicit differentiation,  $\varphi$ ;  $F(x,\varphi(x)) = C$  $\frac{\partial F_{i}}{\partial y_{i}} (x, \varphi(x)) \left( \begin{array}{c} \frac{\partial \varphi_{i}}{\partial x_{2}} \\ \frac{\partial X_{2}}{\partial x_{2}} \end{array} \right) = - \begin{array}{c} \frac{\partial f_{i}}{\partial x_{2}} \\ \frac{\partial Y_{i}}{\partial x_{2}} \end{array}$ (Ejsk Isisk Sist  $\begin{aligned} |\underline{s}_{j} = k & |\underline{s}_{k} = l \leq n & |\underline{s}_{k} \leq n \\ \underline{k}_{k} = k & \underline{k}_{k} \\ \frac{\partial q_{j}}{\partial x_{k}} (x, q_{k}x_{l}) &= \left( \frac{\partial F_{i}}{\partial y_{k}} (x, p_{k}x_{l}) \right)^{-1} \left( -\frac{\partial F_{i}}{\partial x_{k}} (x, q_{k}x_{l}) \right) \end{aligned}$ k×n kxk kxn Special case when k=1. eq (last class) x2+y42=2. (an we solve 2=2(r.y) near (0.1.1) ) F:  $|R^{2+1} \rightarrow |R' \qquad F(x,y,z) = \chi^{2} + y^{2} + 2^{2}$ (1=(0.1) EIR2 b7 EIR' C= F(0.6)=2

 $\frac{\partial f}{\partial z}(0,1,1) = 22|_{(0,1,1)} = 2 \neq 0$ By IFT,  $\exists U \subseteq IR^2$  contains a=0.1,  $\exists V \subseteq IR$  b=1. S.I. 2 Cr Unique function Z:U-V (xy) (> 2(xy)) with 2(0.1)=1 and F(x.y.zoxy) =2 for all KEU. Also Z(r.y) C'. ( We know it is 2= J2-x=y2) More generally,  $F: \Omega \subseteq |\mathbb{R}^{n+1} \longrightarrow |\mathbb{R}^{1}$ F(x.y)= F(x, ... xn.y) Suppose a= (a,...an) EIP, bell, fla.b/=c By IFT, if  $f_{g}(a,b) \neq 0$ , then Za function y=y(x,·-kn) near (a, ·- m) Solving  $f(x_1 \cdots x_n, y) = c$  locally.  $y(a_1 \cdots a_n) = b$ Rink 29 ... 29 can be computed by implicit differential

Special case k=2, n=1. eq (last class)  $x^{2}y^{2}z^{2}=2$  (con we solve  $\chi_{ff} = 1$  g = g(x), f = 1y=yux, 2=20x1?  $F: (R^{1+2} \longrightarrow (R^{2} \longrightarrow (R^{2$ newr (0.1.1)  $\begin{pmatrix} \partial f_{1} & \partial f_{2} \\ \partial f_{3} & \partial f_{4} \\ \partial f_{4} & \partial f_{4} \\ \partial$ : invertible. By J(T, P) = Y(r), 2 = 2(r) near (4.1.1) S.f. (F((r, Y(r), 2(r))) = 2 (F. ( )) = 1 (Y(r)) = 1 (

More generally, 
$$F: \Omega \subseteq \mathbb{R}^{1+1} \to \mathbb{R}^{2}$$
  
 $F(x \cdot q \cdot y_{e}) = \begin{pmatrix} F_{1}(x \cdot y_{1}, y_{e}) \\ F_{2}(x \cdot y_{1}, y_{e}) \end{pmatrix} = \begin{pmatrix} C_{1} \\ C_{2} \end{pmatrix}$   
Suppose (o.b.b.)  $\subseteq \Omega$  softsfle  $F(a_{1}b_{1}, b_{2}) = \begin{pmatrix} C_{1} \\ C_{2} \end{pmatrix}$   
By  $IFT$ ,  $if \begin{pmatrix} B_{1} & B_{2} \\ B_{2} & B_{2} \\ B_{3} & B_{2} \end{pmatrix}$  is invalue,  
 $f_{1} = \frac{1}{2} \frac{$ 

$$\frac{1}{2^{2} \pm 0} \int_{1}^{\infty} \frac{1}{2} = 20^{\circ} \int_{1}^{\infty} \frac{1}{2} \int_{$$

Similar completion; JFT cays xig rea  
le expressed as functions = 2.  
Is y=g(x1. Z=2(x) possible?  
det 
$$\begin{vmatrix} 4 & 3 \\ 4 & 3 \end{vmatrix} = 0$$
. Join this case, we could  
determine it y, & can be expressed as  
functions on x near (2.1.4) from IFT.  
Rok JJ y=y(x1, Z=2(x) near (2.1.4) exist  
and differentiable, by taking implicit differentiats  
(a 3) (dyde) = (-1). This (man  
system has no solution. =) contradiction.  
Rok Jumplicit function theorem has anony implicit  
applicit differentiable  
(a j) (dyde) = (-1). This (man  
system has no solution. =) contradiction.  
Rok Jumplicit function theorem has anony important  
applicit differentiable  
(a j) (applicit function theorem has anony important  
(applicit differentiable  
(a j) (applicit function function function for any important  
(applicit differentiable)

Infact, Inverse Aunchion theorem is equivalent to Implicit function theorem. Rink  $f:\mathbb{R}^2 \to \mathbb{R}^2$   $f(x,y) = (x^2 - y^2, 2xy)$ 9 since f(x,y)= f(-x,-y) hence f is not injective and it has no global inverse. (i, -1) (i, $Df(x,y) = \begin{pmatrix} 2x & -2y \\ 2y & ex \end{pmatrix}$ and det Of(xy) = 4x<sup>2</sup> fay<sup>2</sup>>0 for (x.y) \$ (0,0). By Inverse function theorem, It is locally invertible with differentiable local inverse

e.g. let g(u.v) be a local inverse of fixing Near (1, -1). Then g(0, -2) = (1, -1) $Dg(0,-2) = Df(1,-1)^{-1} = \begin{pmatrix} 2 & 2 \\ -2 & 2 \end{pmatrix}^{-1} = f(1,-1)^{-1} = \begin{pmatrix} 2 & 2 \\ -2 & 2 \end{pmatrix}^{-1} = f(1,-1)^{-1}$ In fact, we can flued glu.v) explicitly. Rink  $\begin{cases} u = x^{2}y^{2} & Near (1, 7), x \neq 0 \\ v = 2xy & hence \quad y = \frac{v}{3x} \end{cases}$  $\Rightarrow u = x^2 - (\frac{\gamma}{1x})^2$ =) 4x + - 4ux - 2 = 0  $\Rightarrow \chi^{L} = 4u \pm \sqrt{(-\alpha u)^{2} - 4 \cdot 4 \cdot (\cdot v)^{2}}$  $= \underbrace{UE \int u^2 + v^2}_{2}$ Put (x.y)= (1,-1) and (U.V) = co.-2) 

 $= \frac{1}{2} \frac{$ In both Implicit & Inverse function Rul theorems, we assume a Jacobian motion to be invertible. Without this assumption, the fheoreus are in conclusive. Consider a set of points S ( Kiy, U.V) E #4 Genise Satisfying xu + yvu = 2 $xu + y^2v = 2$ (a) Show that near (1.1.1.1) there exist a differentlashe function (u.v)=f(x.y) s.t. S is a graph of f. (6) Compute du dy nt (1.1.1.1).

$$(Sull (a) F(X,Y,U,U) = (F_1, F_2) = (XU + YVU^{+}, XU^{3} + Y^{9})^{4}$$

$$(G_1, (I, I, I) = (2, 2)$$

$$\begin{pmatrix} \partial f_1 & \partial f_1 \\ \partial U & \partial V \\ \partial f_2 & \partial F_2 \\ \partial U & \partial V \end{pmatrix} = \begin{pmatrix} X + 2YVU & YU^{+} \\ 3XU^{+} & 4Y^{+}V^{3} \end{pmatrix}^{4}$$

$$(I, I, I) = \begin{pmatrix} X + 2YVU & YU^{+} \\ 3XU^{+} & 4Y^{+}V^{3} \end{pmatrix}^{4}$$

$$= \begin{pmatrix} 3 & 1 \\ 3 & 4 \end{pmatrix}$$

$$det \begin{pmatrix} 3 & 1 \\ 3 & 4 \end{pmatrix}$$

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$$det \begin{pmatrix} 3 & 1 \\ 3 & 4 \end{pmatrix}$$

$$det \begin{pmatrix} 3 & 1 \\ 3 & 4 \end{pmatrix}$$

$$(I, I, I) \qquad (I, I, I)$$

$$Heare exist a differentiable fixes free free exist a differentiable fixes free exist a free ex$$

of CI.I.I.I.  $\frac{1+3\frac{\partial u}{\partial x}+\frac{\partial v}{\partial x}=0}{1+3\frac{\partial u}{\partial x}+4\frac{\partial v}{\partial x}=0}$  $\begin{pmatrix} 3 \\ 3 \\ 4 \end{pmatrix} \begin{pmatrix} \overline{\partial x} \\ \overline{\partial x} \\ \overline{\partial y} \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$  $\begin{pmatrix} 3\mu\\ 3\bar{\mu} \end{pmatrix} = \begin{pmatrix} -\frac{1}{3} \\ 0 \end{pmatrix}$ <u> 2 (nu)</u> = U-- 1 Ju xu + yvu=2  $\frac{\partial (y w^2)}{\partial x} = y \cdot \frac{\partial v}{\partial x} \cdot u^2 + y v \cdot \frac{\partial u^2}{\partial x}$  $= y u^2 \mathcal{J}_{\mathcal{F}} + y v_2 u \mathcal{J}_{\mathcal{F}}$